



HONG KONG ASIAWORLD-EXPO 亞洲國際博覽館 3<sup>RD</sup> TO 6<sup>TH</sup> DECEMBER 2025



# Application Effect of Artificial Intelligence Visual Recognition System on the Receiving and Inventory Process of Loaner Instruments

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**A Background and Objective** 

**B** Research Details

C Research Method and Data Collection

**D** Result Analysis

**E** Recommendation

**F** Conclusion and Implication







## A. Background and Objective

## **Research Background**





On loan instruments: Reprocessing process is complex, challenging, but related to patient safety



## A. Background and Objective Clinical Background Analysis

#### **Growth in operations and instrument usage**



With the continuous advancement of medical technology and the increase in patient demand, the number of surgeries has shown an increasing trend year by year; in order to adapt to diverse surgical needs, the use of on loan instruments has become more and more frequent.

#### **Challenges and limitations of manual counting**



The traditional manual inventory model has many challenges and limitations, such as low efficiency and accuracy greatly affected by human factors, which makes it difficult to meet the dual pressures of medical quality and safety requirements and efficiency improvement.

Manual handover mode: cumbersome process, manual counting, easy to get confused, incomplete traceability





## A. Background and Objective Clinical Background Analysis

Current bottlenecks and pain points during receipt of loan instruments

#### **Operation**

- Inefficiency: time
   Consuming
- Manpower requirement
- Low turnover rate;
- Information not shared

#### **Quality Control**

- High risk of error
- Difficulty in tracing
- Risk of foreign body left behind;
- Equipment management costs

#### **Staff Safety**

- Visual fatigue: wrong sight and missed sight
- Human fatigue leading to mis recording and omission
- High staff pressure
- Low satisfaction

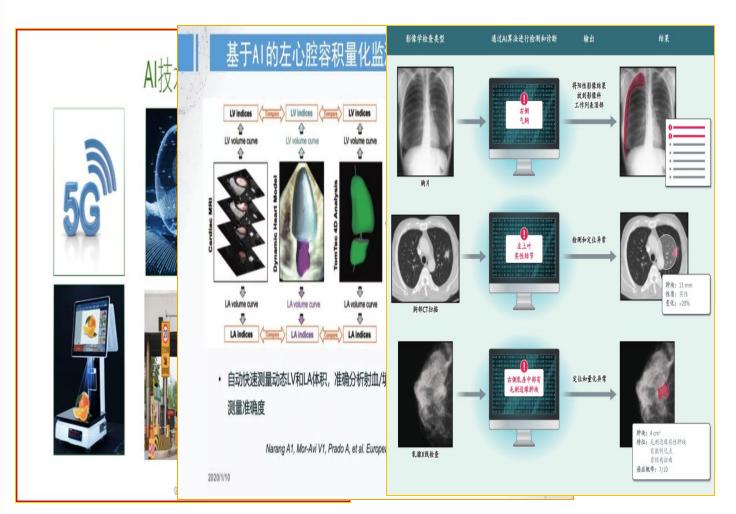
Low operational efficiency, increased safety risks, and difficulty in quality control





## A. Background and Objective

## **Technology Development**



#### **Current Status of Computer Vision Technology**

Computer vision technology is increasingly used in the medical field, and it has shown great potential in medical image recognition and diagnosis.

#### **Progress in Deep Learning Object Recognition**

Deep learning algorithms have made recent progress in object recognition, providing strong technical support for artificial intelligence visual recognition systems.

From Assisted Tools to Transformative Cores -- The Al Era







## A. Background and Objective Literature review

中华医院感染学染点 2023 年第 23 泰第 2 期 Chin J Nosocomiol Vol. 23 No. 2 2022

doi:10,11816/cn.ni,2023-221390



· 论 著·

开放科学(資源服务)标识码(OSID), LEGAL

人工智能系统在外来医疗器械交接中 应用效果的多中心研究

护士进修杂志 2024 年 1 月第 39 卷第 2 期

#### 人工智能视觉识别系统在外来医疗器械检查中 的应用效果

吴小娜 陈慧 何倩 刘佳微

(四川大学集西医院/集西护理学院 法浆消毒供应中心。四川 成都 610041)

编 票 目的 经过人工领债等受证别系统在济泰供应由人(CSSD)基本非其形容别被包装货量的应用效果 方法 我院于 2022 年 1 月将采集在 CSSD 处置的骨科并来器被信息,包括(图像、名称规格、数量)等传送至人工智 能報管認知系統中存档, 完理图像数据分析与问题, 归档预整提示。 關決取 2021 年 2-12 月系统应用前费能消毒 供应中心接收处理的 9 500 似份科外来器械为对照相。2022年1月-11月系统应用后的 9 500 似为观察相。比较 2组医疗器械包装质量及管理工作情况(包装质量,平均耗时,使用满意度)。 结果 观察组医疗器械包装质量优于 对照组, 差异有维计学意义(P<0.05): 如装平均耗时及使用滴定度使干对照组, 差异有维计学意义(P<0.05)。 **结** 论 人工智能视觉识别系统在 CSSD 外来骨科医疗器械包装环节,核查应用中效果较好。提升包装质量的同时,也 伊伊了基本作科医疗器械管理按照 提高了手术安徽音度和工作效率

美體調 清毒供应中心; 人工智能; 视觉识别; 外来骨科医疗器械; 包装质量

#### Research and application of artificial intelligence visual recognition system in inspection package quality of external medical instruments in disinfection supply center

(Washing and Disinfection Supply Center , West China Hospital & West China School of Nursing

Sichnan University , Chengdu 610041 , Sichnan , China)

Abstract Objective To explore the application effect of artificial intelligence visual recognition system on the packaging quality of external orthogedic medical devices in the Central Sterile Supply Department (CSSD), Method In January 2022, information on external orthopedic instruments disposed by CSSD were collected in our hospital. packages of orthopedic external instruments received and processed by CSSD of our hospital before the system appli cation from February to December 2021 were selected as the control group, and a total of 9,600 packages after see tem application were selected as the observation group. The quality and management of medical device packaging of medical device packaging and satisfaction with use in the observation group were better than those in the control group, and the difference was statistically significant (P<0,05). The average packaging time was lower than that of the control group, and the difference was statistically significant (P<0,05), Conclusion The artificial intelligence visual recognition system has shown good effectiveness in the packaging process of CSSD external orthopedic medical devices. While improving packaging quality, it has also optimized the management process of external orthopedic medical devices, and improved operating room satisfaction and work efficiency,

Keywords central sterile supply department; artificial intelligence; visual identity; foreign orthopedic medical devices; packaging quality

中国分类号: R472 文献标识码: C DOI: 10.16821/j.cnki.hsjx.2024.02.010

作書簡介:吴小鄉(1987-),女,四川成都,本科,主管护師,研究方向:医院感染及器械消毒灭菌 通信作者: 陈 慧 , Email , chenhui-comet@ 126, con

#### scientific reports

OPEN An efficient annotation method for image recognition of dental

instruments

Shintaro Oka (\$135), Kazunori Nozaki (\$152) & Mikako Hayashi (\$153)

To prevent needlestick injury and leftover instruments, and to perform efficient dental tre is important to know the instruments required during dental treatment. Therefore, we wi

## Artificial intelligence model for automated

surgical instrument detection and counting: an experimental proof-of-concept study

Ekamjit S. Deol<sup>1</sup>, Grant Henning<sup>1</sup>, Spyridon Basourakos<sup>1</sup>, Ranveer M. S. Vasdev<sup>1</sup>, Vidit Sharma<sup>1</sup>, Nicholas L. Kavoussi<sup>2</sup> R. Jeffrey Karnes<sup>1</sup>, Bradley C, Leibovich<sup>1</sup>, Stephen A. Boorjian<sup>3</sup> and Abhinav Khanna<sup>14</sup>

mensined surgical items (RSIs) are surgical instruments or materials unintentionally left inside a patient's body there surgery [1]. RSIs are considered "never events," rhich are defined as serious, preventable incidents that hould ideally never occur in healthcare settings [2], septie increased efforts to prevent RSIs, they remain a publicant problem, with an available. espite increased efforts to prevent RSIs, they remain a gnificant problem, with an estimated incidence of 1 in every 3800 surgeries [3]. The impact of RSIs on patients, realthcare providers, and the healthcare system is sub-antial, inciding physical and psychological harm to attents, emotional distress for surgeons, and increased subhocare ports.

heare costs [4].

difficulty programs for preventing RSIs center and manual counting of surgical items, commonshy the control by narring staff [5, 6]. However, such prosorted by narring staff [5, 6]. However, such prosorted presented staff [6, 6]. However, such presorted presorted staff [6, 6]. However, such presorted staff [6, 6]. Ho

evaluate the feasibility and performance of a deep learn-ing-based computer vision model for automated surgical tool detection and counting. The study was performed

Primary and secondary outcomes

The primary outcome was the model's performat
detecting and classifying suggical tools, as measu
precision, recall, and mean average precision, sta
measures to benchmark the performance of con

model achieved a precision

100%. Precision remained

tiating between surgical t scalpels to 100% for basins

forceps to 98.2% for retract

the overlapping tool subse

shows examples of predicti

In a real-time surgical v

tained a correct surgical t

model for the

surgical instruments. The

the model could keep pace with the dynamic nature of a surgical procedure, correctly identifying tools as they are being used in real-time. All data analysis was conducted in Python using the PyTorch and Ultralytics packages

Deol et al. Patient Safety in Surgery

The overall dataset consisted of 1004 images, of which 603 (7891 tool instances) images were used for model training, 201 (2667 tool instances) for internal validation, and 200 (2655 tool instances) for testing model perforframes, across tool switche mance. For detecting the presence or absence of surgical surgery. The model achiev tools in the test dataset the model made 2.693 surgi- of 24.7 ms (IOR: 3.1 ms) cal tool predictions, of which there were 41 instances in time 1:00:07 h), correspond which the model falsely identified the background as a (IQR: 4.9) on a single NVII surgical tool (false positive). Thus, the overall precision the model's ability to maint for practical applications in for distinguishing surgical tools from the background was 98.5%. Conversely, the model failed to identify a surplementary Table 1. gical tool in only three instances, incorrectly labeling a tool as background in all three instances (false negative). This translates to an overall recall (sensitivity) of 99.9%. This study demon The model's mean average precision 50-95 was 88.4%, of employing and mean average precision 50 was 99.4%.

Model performance was also explored for differentiating between the 11 types of surgical instruments. The basin class exhibited a precision and recall of 100%, indicating that the model perfectly predicted all basin instances without any false positives or false negatives. 94.0% and a recall of 97.1%. The precision and recall values for the remaining instrument classes can be found in Table 1, and a confusion matrix illustrating these results

Similar model performance was observed on the subset of test images containing overlapping tools. For

Table 1 Precision and recall values for each of 11 surgical

| instrument classes |               |            |
|--------------------|---------------|------------|
| Instrument Class   | Precision (%) | Recall (%) |
| Scalpel            | 94.02         | 97.12      |
| Surgical skin pen  | 98.19         | 99.39      |
| Surgical scissors  | 99.24         | 99.62      |
| Forceps            | 95.21         | 98.93      |
| Hemostat           | 98.60         | 99.65      |
| Needle driver      | 97.97         | 99.66      |
| Retractor          | 98.88         | 99.25      |
| Beaker             | 97.39         | 100.00     |
| Syringe            | 99.60         | 100.00     |
| Surgical gauze     | 99.26         | 100.00     |
| Basin              | 100.00        | 100.00     |

#### Discussion

This study demonstrates the feasibility and effectiveness of employing a deep learning-based computer vision model for the automated detection and enumeration of surgical instruments. The model achieved high precision and recall in distinguishing surgical tools from the background and in differentiating between various surgical instruments, even in challenging scenarios involving overlapping tools. In a real-time surgical video analysis, the model maintained a correct tool count during all non-transition times with an inference speed suitable for real-time use. These results highlight the potential for computer vision models to maintain an automated tool count during surgery which has the potential to reduce errors and thereby help improve surgical safety.

Our study's high presicion and recall in detecting a

sion and recall in distinguis sion and recall in distinguishing surged tool background and in differentiating between var cal instruments, even in challenging scenarios involv overlapping tools. In a real-time surgical video analysis Syringes also achieved a precision of 99.6% and a recall the model maintained a correct tool count during all of 100%, demonstrating nearly perfect performance in non-transition times with an inference speed suitable for identifying all syringe instances. The surgical scissors real-time use. These results highlight the potential for class attained a precision of 99.2% and a recall of 99.6%. computer vision models to maintain an automated tool In contrast, the scalpel class had the lowest precision at count during surgery which has the potential to reduce errors and thereby help improve surgical safety.

Our study's high precision and recall in detecting a broad array of surgical tools, even in challenging conditions with overlapping items, address some of the criti cal gaps in previous research, such as the need for robust detection across a diverse range of surgical objects and the demonstration of an inference speed suitable for practical real-world applications. Lavado et al. previously developed a computer vision model based on YOLOv3 for detecting surgical tools in cluttered trays and performed occlusion reasoning to determine which tool should be removed first following sterilization [24]. Their model was trained on only four different surgical tool classes and performed moderately well (mean average precision at 0.50 of 92.0%). In contrast, our model wa trained on 11 different classes and achieved a mean average precision at 0.50 of 99.4%. Also, of note, Lavado et al photographed surgical tools in a metallic background, whereas our models were trained on tools in a blue surgi cal cloth background, which is similar to most real-world









## A. Background and Objective Research Objective Setting

AIM: The application effect and value of artificial intelligence visual recognition system in the CSSD loaned instruments receiving and inventory process

improvements of AI visual recognition systems in counting loaned instrument to ensure efficient and accurate medical processes.



personnel acceptance of system implementation, providing strong data support for decision-making .

#### **Long Term Goal**

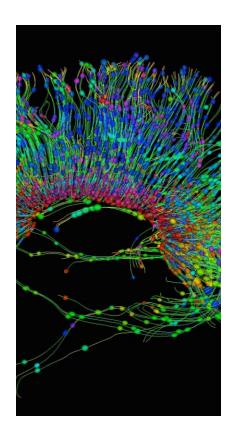
Establish standardized processes and quality control systems for intelligent equipment inventory to promote intelligent development in the medical field.







## **System Technical Principles**









#### **Convolutional Neural Networks**

In device image recognition, convolutional neural networks\* automatically extract image features to achieve high-precision classification, providing technical support for foreign device recognition.



#### **Deep Learning Algorithms**

The algorithm module adopts advanced deep learning algorithms to continuously optimize the recognition model and improve the accurate recognition rate of instrument images under complex backgrounds.

Note\*: A convolutional neural network is a type of artificial neural network specifically designed to process data with a grid-like structure, most notably images. Through a unique operation called convolution, it can efficiently identify spatial patterns in images, such as edges, corners, object parts, and even entire objects.







## **System Structure**

# Hardware composition



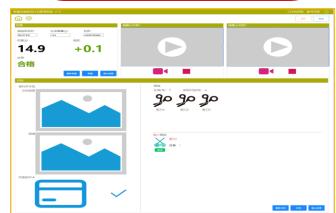
The system is equipped with high-definition cameras to capture clear images; the computing unit quickly processes recognition tasks; and the display terminal intuitively displays the results to ensure convenient operation.



# Software System

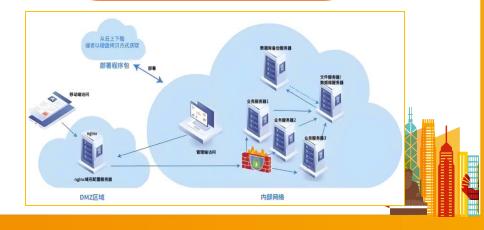


The image acquisition module enables efficient capture; the core of the recognition algorithm module is responsible for deep learning and model reasoning; the data management module ensures data integrity and security.



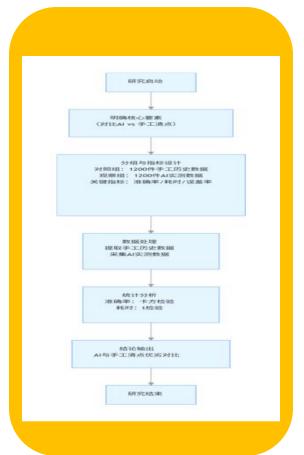
## Network Architecture

Adopting a local deployment solution, data and processing equipment are stored locally to ensure data security and privacy, reduce network dependence, and improve system stability and response speed.





## **Workflow Design**



Standardized collection process

Establish detailed instrument image acquisition standards, including lighting, angle, resolution, etc., to ensure consistent image quality and lay a solid foundation for identification.

Collaborative identification mechanism

The system identifies the device in real time and quickly feeds back the results; at the same time, a manual review channel is established to conduct a second confirmation of suspected errors or complex devices.

# **Exception handling**process

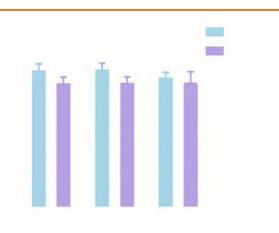
Clarify the responsibilities and processes for exception handling, such as the response measures for blurred images, recognition failures, etc., to ensure that errors are corrected and handled in a timely manner.







## **Study Design**



#### **Controlled trial plan**

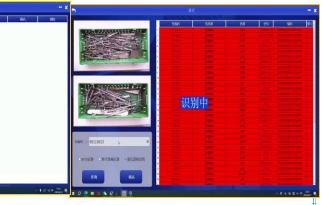
A control group and an experimental group were set up. The control group adopted the traditional manual counting mode, and the experimental group adopted the AI visual recognition system. The counting efficiency and accuracy of the two groups were compared.





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## **Research Subject**

**Inclusion** criteria for on loan instrment

The study was limited to devices of specific types, materials, and complexity to ensure the effectiveness and accuracy of the identification process and avoid interference from non-target devices.

Personnel training and operating procedures

Researchers need to receive unified training to ensure standardized operations, reduce human errors, and ensure the accuracy and reliability of research data.







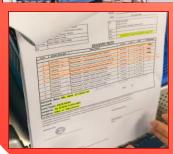
## C. Research Method and Data Collection

#### **Research Method**

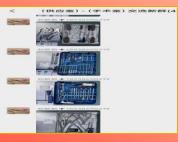
Comparison between traditional methods and artificial intelligence recognition

#### **Traditional Method**









**Artificial intelligence recognition** 









## C. Research Method and Data Collection

## **Method of Data collection**

#### **Main evaluation indicators**

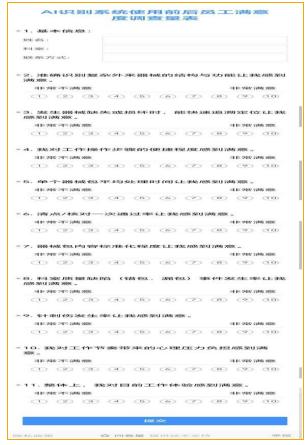
Recognition accuracy, inventory time, and error rate are used to comprehensively evaluate the performance of the AI visual recognition system to ensure that the data is accurate and effective.

#### **Data collection time and frequency**

Collect data in real time and record key indicators at high frequencies to ensure the timeliness and integrity of data and provide a basis for system optimization.

#### **Quality control and data review**

Establish a strict quality control system, conduct multiple audits on the data to ensure its accuracy and reliability and eliminate outliers.



| 2   |                | 植入物与外                | 来医疗器 | 械接收清 | 点环节 | 查检表   |              |          |             |          |
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| 5.0 |                |                      |      |      |     |       |              |          |             |          |
| 27  |                |                      |      |      |     |       |              |          |             |          |
| 28  |                |                      |      |      |     |       | 总包数:         |          |             | <u> </u> |
| 29  |                |                      |      |      |     |       |              |          |             |          |







## C. Research Method and Data Collection

## **Statistical Case Study**



#### Sample size calculation and efficiency evaluation

Based on previous data and expected effect size, accurately calculate the required sample size and evaluate the power of statistical tests to ensure reliable results.

#### **Descriptive statistical analysis**

Descriptive statistical analysis is conducted on the main indicators to reveal the data characteristics and lay the foundation for subsequent in-depth analysis.





#### Statistical methods for intergroup comparisons

Appropriate inferential statistical methods were used to compare the differences in main indicators between different groups and reveal the advantages of the AI visual recognition system.

#### Paired Samples Statistics

|                  | Mean value (E) | Number | Standard  | Mean standard |
|------------------|----------------|--------|-----------|---------------|
|                  |                |        | deviation | Error         |
| Pair 1 - Control | 85             | 47     | 5.473     | .798          |
| group            |                |        |           |               |
| Research group   | 98             | 47     | 2.126     | .310          |

#### Paired Samples correlation

|                       | Number | correlation | Significance |
|-----------------------|--------|-------------|--------------|
|                       |        | coefficient |              |
| Pair 1. Control group | 47     | 015         | .921         |
| & research group      |        |             |              |

#### Normality test

|            | Kolmog     | Smirnov(K)a | Shapiro-Wilk |            |    |              |
|------------|------------|-------------|--------------|------------|----|--------------|
|            | statistics | df          | significance | statistics | df | significance |
| difference | .077       | 47          | .200*        | .979       | 47 | .553         |

- $\ensuremath{^{*}}.$  The lower limit of true significance
- a. Lilliefors significance correction







## **D. Result Analysis**

## **Major Results Analysis**

#### Al system recognition accuracy

The AI system's recognition accuracy is as high as 99.2%, significantly better than the 88% of traditional methods.

#### Improved inventory efficiency

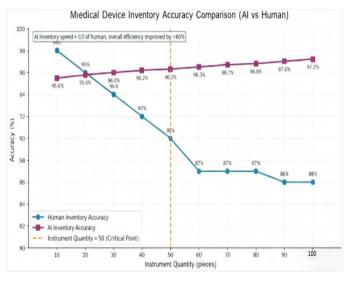
The AI system improves inventory efficiency, effectively shortens working time and improves overall efficiency.

## **Differences in device recognition performance**

There was a significant difference in recognition performance between simple and complex instruments, but the impact on overall accuracy was minimal.

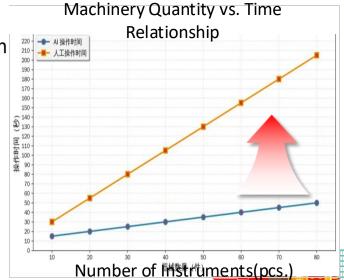
## Average time/pack for counting instrument before and after using the AI recognition system

| pachages    | Experimet group         | Control group           | Z-score               | P-score |
|-------------|-------------------------|-------------------------|-----------------------|---------|
|             | (AI)                    | (manual)                |                       |         |
|             | (n=1200)                | (n=1200)                |                       |         |
| <20         | 10. 70 (9. 80, 11. 70)  | 22. 40 (20. 90. 23. 62) | -13.598 <sup>b</sup>  | ≪0.001  |
| pcs/package | 10. 10 (9. 80, 11. 10)  | 22. 40 (20. 90, 23. 62) | -13.096               | ~0.001  |
| (n=246)     |                         |                         |                       |         |
| 20-50       | 05 05 (00 00 40 00)     | ()                      | -25, 434 <sup>b</sup> | ≪0.001  |
| pcs/package | 36. 25 (33. 20, 40. 30) | 92. 40 (89. 20, 95. 30) | -25. 434              | < 0.001 |
| (n=862)     |                         |                         |                       |         |
| >50         | 56. 75 (54. 32, 59. 17) | 146.50 (142.22, 150.47) | -8. 331 <sup>b</sup>  | ≪0.001  |
| pcs/package | 00. 10 (04. 32, 59. 11) | 140.00(142.22,180.47)   | -0. 331               | ~0.001  |
| (n=92)      |                         |                         |                       |         |
|             |                         |                         |                       |         |



## The accuracy of counting instrument packages before and after using the AI recognition system

| Classification   | Indicator     | Experimet group (AI) | Control group<br>(manual) | X <sup>z</sup> value | P-score |
|------------------|---------------|----------------------|---------------------------|----------------------|---------|
|                  |               | (n-1200)             | (n - 1200)                |                      |         |
| < 20             | Accuracy rate | 044 (00 00)          | 007 (00 30)               |                      | 0.0001  |
| pcs/package      | of Instrument | 244 (99.2%)          | 237 (96.3%)               |                      | 0.039   |
| (n <b>-</b> 246) | inventory(%)  |                      |                           |                      |         |
| 20-50            | Accuracy rate | 005 (00 00)          | 000 (00 00)               |                      |         |
| pcs/package      | of Instrument | 835 (96.9%)          | 803 (93.2%)               | 22. 881              | < 0.001 |
| (n <b>-</b> 862) | inventory(%)  |                      |                           |                      |         |
| > 50             | Accuracy rate |                      |                           |                      |         |
| pcs/package      | of Instrument | 88 (95.7%)           | 80 (87.0%)                |                      | 0.021   |
| (n <b>-</b> 92)  | inventory(%)  |                      |                           |                      |         |







## **D.** Result Analysis

## **Secondary Outcome Analysis**

Costs and benefits of System Utilization

Staff acceptance and satisfaction

System stability and reliability

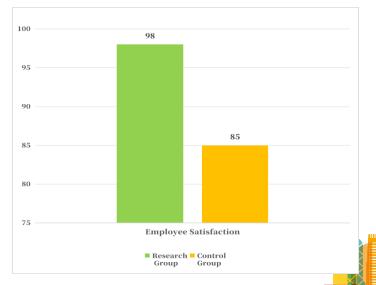
#### Traceability system management quality

| indicator  | Experimet group(AI) | Control group<br>(manual) |
|--|---------------------|---------------------------|
| The completion of instrument inventory work can<br>be ensured to be recorded         | Y                   | N                         |
| The information on the type an quantity of instruments can be ensured to be recorded | Y                   | N                         |
| It can facilitate the implementation of full-process quality traceability            | Y                   | N                         |
| Can it reduce the operational difficulty for staff?                                  | Y                   | N                         |
| Can it display the usage information in real time?                                   | Y                   | N                         |

## Employee satisfaction before and after using the AI recognition system

| indicator             | Experimet group(AI) (n=47) | Control group (manual) (n=47) | t-score | P-scroe |
|-----------------------|----------------------------|-------------------------------|---------|---------|
| Staff<br>Satisfaction | 98.00±2.126                | 85.00±5. <b>47</b> 3          | -15.102 | <0.001  |







## **D. Result Analysis**

## **Abnormal situation analysis**

## Case study on Identification failure

Conduct in-depth analysis of cases of recognition failure to identify reasons including poor instrument image quality and difficulty in recognizing special materials.

## **Systematic Errors** and Human Factors

By comparing recognition failure cases caused by system errors and human factors, the difference between the two and their respective proportions can be clarified.

# Verification of the effectiveness of improvement measures

Based on the analysis of the causes of recognition failure cases, improvement measures are proposed and implemented, such as optimizing the image acquisition process and enhancing the ability to recognize special materials.



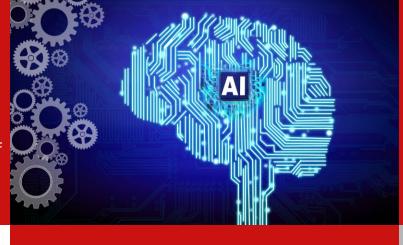




## E. Recommendation Technical optimization suggestions

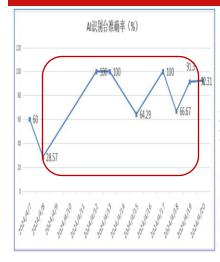
#### **Algorithm model optimization**

Continuously collect data, optimize algorithm models, improve recognition accuracy and efficiency, and ensure the ongoing enhancement of Al system performance.



## System integration and compatibility

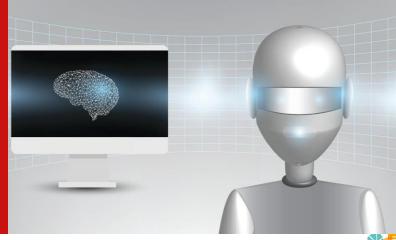
Strengthen system integration capabilities, improve compatibility with other medical systems, and realize data sharing and process collaboration.





#### Hardware equipment upgrade

As technology develops, timely upgrades to high-definition camera equipment, computing units and other hardware to ensure system speed and stability.





## E. Recommendation

#### **Process Enhancement Recommendations**

# Image acquisition specifications

Develop detailed standardized image acquisition specifications to ensure image quality and reduce recognition errors caused by unclear images.

# 基于XXX实现器械识可视化信息展示 快速精准识别器域 提供可视化器域信息 编助操作人员熟悉器 提供相关注意事项,操作

# Human-machine collaborative optimization

Optimize the human-machine collaborative working mechanism, clarify the responsibilities and interaction methods between AI systems and personnel, and improve overall work efficiency.







## E. Recommendation





## **Training and promotion**

## **Operator training**

Design training courses for operators, covering basic operation, maintenance and troubleshooting of AI systems to improve personnel skills.

#### **Industry promotion**

Formulate a multi-center promotion and application strategy, pilot it in some hospitals first, and then gradually expand it to a wider area after summarizing the experience.





## F. Conclusion and Implication Main Research Conclusions

#### **Al Vision Advantages**

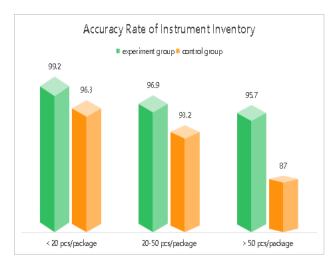
Accurate identification, efficient inventory, reduced labor costs, and improved CSSD efficiency and quality .

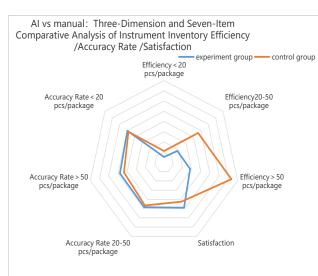
#### **Limitation Factor**

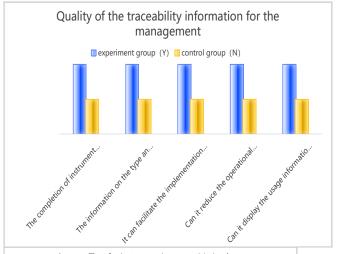
The technical threshold is high, the equipment cost is high, customization is required, and it is greatly affected by environmental factors.

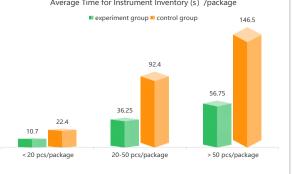
#### **Technology Outlook**

As technology matures and costs decrease, the application prospects of AI visual recognition systems are broad and will lead to innovation and upgrading of CSSD management.















## F. Conclusion and Implication

## **Practical Significance**







#### **Management Implications**

The AI visual recognition system helps the disinfection supply center achieve process optimization and intelligent management, improving work efficiency and quality.



# **Contribution to medical safety**

Through accurate identification and efficient inventory, we can reduce medical risks, strengthen the medical quality and safety line, and protect patient safety.





## F. Conclusion and Implication

# Research Limitations and Prospects

**Limitation Analysis** 



Research Direction



The sample size of this study is limited and does not cover all types of devices; the scope of research needs to be expanded in the future to consider more influencing factors.

Explore the application effects of AI visual recognition systems in different medical institutions and design more efficient algorithms and processes •

Follow-up Evaluation

Continuously monitor system performance and results, adjust optimization plans in a timely manner, and ensure the timeliness and practicality of research results.



## Thank you for your attention



3<sup>RD</sup> TO 6<sup>TH</sup> DECEMBER 2025

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